ICFP Contest 2021

Specification v2.1

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1   Introduction

After cleaning up bit rot in underground mines and communicating with aliens, an era of peace and leisure has arrived in Lambda land. This has lead to a number of TV game shows really taking off. One of these is **Brain Wall**, a contest originating in Japan. Many local versions of this have aired across the globe and it is sometimes better known as **Human Tetris** or **Hole in the Wall**.

Figure 1: Screen capture of the TV Show

An automated system moves a styrofoam wall towards the player. This wall has a hole cut out, and the goal of the game is to assume a position with your body that allows you to fit through the hole in the wall. But just fitting through the hole is not enough: in our variation, fully automated judges will count the number of dislikes, which the participants try to minimize.

More background information about **Brain Wall** can be found on the wikipedia page. You can also watch some samples of the TV show on youtube.

2   Updates

Note that there will be updates to this specification, and more problems will be released during the contest. This will happen at these specific times:

- 12 hours into the contest (new problems only, no changes to specification)
- 24 hours into the contest (after the lightning division ends)
- 36 hours into the contest
- 48 hours into the contest

We may also release smaller clarifications on the FAQ page.

2.1   Changelog

- **v1.1** at 9 July, 12:43 UTC: Clarified that we only consider the last pose for each problem for each team.

- **v1.2** at 10 July, 00:00 UTC: Added HTTP API endpoint to obtain info about submitted solutions.

- **v2.0** at 10 July, 12:00 UTC: Added bonus system with `BREAK_A_LEG` and `GLOBALIST`.

- **v2.1** at 10 July, 14:13 UTC: Fixed naming inconsistency with d and d' in `GLOBALIST` constraint.

3   Problem definition

The goal is to assume a **pose** with a given **figure** so that it fits into the given **hole**, while scoring as many points as possible.

The figure and hole are both located on a two-dimensional grid. They both consist of line segments that all start and end at a point with integer X and Y coordinates.
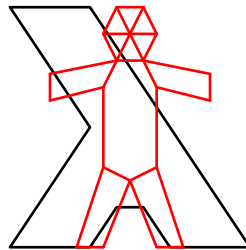

Figure 2: The "Lambdaman" problem

A hole is always a simple polygon: this means the line segments of the hole will not intersect, and there will be no further holes within the hole. A figure consists of line segments that may connect to other line segments at the start and end points.

Assuming a pose works by moving the start and end points of line segments into a new configuration. This is of course not without constraints, since our stick figures cannot break the laws of physics!

We require that:

(a) If line segments connect in the original figure, they must also connect in the assumed pose. The list of connections is explicitly indicated in the problem.

(b) Edges cannot be compressed or stretched arbitrarily. The amount that an edge can be stretched depends on the original edge length.

   We define the squared distance d in between two points p and q as:

$$d(p,q) = (p_x - q_x)^2 + (p_y - q_y)^2$$

Let's assume an edge between vertices v_i and v_j exists the original figure, and v_i' and v_j' are the new positions of these points in the assumed pose.

We then require that the ratio between the two squared lengths is at most $\varepsilon/1,000,000$ away from 1:

$$\left|\frac{d(v_i', v_j')}{d(v_i, v_j)} - 1\right| \leq \frac{\varepsilon}{1,000,000}$$

ε is an integer specified per problem.

Furthermore, if a pose is to be considered by the judges, the figure must of course fit in the hole once the figure assumes the pose.

(c) Every point located on any line segment of the figure in the assumed pose must either lay inside the hole, or on its boundary.

When all these constraints are satisfied, the automated judges will count the number of dislikes based on how well the pose fits in the hole. The judges prefer participants who take risk and place figure parts close to every corner of the hole.

For every vertex h in the hole, we take the squared distance to the nearest vertex v in the pose assumed by the figure and then add up those distances.

$$\text{dislikes}(hole, pose) = \sum_{h \in hole} \min_{v \in pose} d(h, v)$$
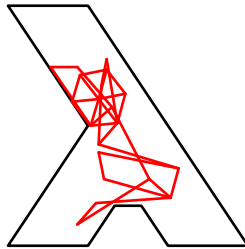
A lower number of dislikes is better.

Figure 3: A possible pose for to the "Lambdaman" problem

4 Submission

4.1 Wire format

Problems and poses are encoded in JSON. A complete example of a problem is given at the bottom of this section.

Points Points are encoded as a JSON array holding the X and Y coordinate, in that order. Coordinates are always integers.

Hole A hole is encoded as a JSON array containing all vertices of the hole in order. The minimum number of vertices is 3.

Figure A figure is encoded as a JSON object with two properties:

- `vertices`: An array of points, indicating the initial locations of the vertices. The minimum number of vertices is 2.

- **edges**: An array of pairs, where each pair represents a line segment between the two vertices. The pairs are given as two 0-based indices into the `vertices` array. The pairs can be specified in either order. The minimum number of edges is 1.

Problem A problem is encoded as a JSON object with the following properties:

- `hole`: A **hole** as defined above.
- `figure`: A **figure** as defined above.
- `epsilon`: The ε used for this problem.

Pose A pose is encoded as a JSON object with a single property:

- `vertices`: An array of points, indicating the new positions of points in the assumed pose.

4.1.1 Example

As a full example, here is the JSON encoding of the "Lambdaman" problem.

```
{
  "hole": [
    [55, 80], [65, 95], [95, 95], [35, 5], [5, 5],
    [35, 50], [5, 95], [35, 95], [45, 80]
  ],
  "figure": {
    "edges": [
      [2, 5], [5, 4], [4, 1], [1, 0], [0, 8], [8, 3], [3, 7],
      [7, 11], [11, 13], [13, 12], [12, 18], [18, 19], [19, 14],
      [14, 15], [15, 17], [17, 16], [16, 10], [10, 6], [6, 2],
      [8, 12], [7, 9], [9, 3], [8, 9], [9, 12], [13, 9], [9, 11],
      [4, 8], [12, 14], [5, 10], [10, 15]
    ],
    "vertices": [
      [20, 30], [20, 40], [30, 95], [40, 15], [40, 35], [40, 65],
      [40, 95], [45, 5], [45, 25], [50, 15], [50, 70], [55, 5],
      [55, 25], [60, 15], [60, 35], [60, 65], [60, 95], [70, 95],
      [80, 30], [80, 40]
    ]
  },
  "epsilon": 150000
}
```

And this is the JSON encoding of the pose in the figure we saw earlier:

```
{
  "vertices": [
    [21, 28], [31, 28], [31, 87], [29, 41], [44, 43], [58, 70],
    [38, 79], [32, 31], [36, 50], [39, 40], [66, 77], [42, 29],
    [46, 49], [49, 38], [39, 57], [69, 66], [41, 70], [39, 60],
    [42, 25], [40, 35]
  ]
}
```

4.2 How to submit poses

Poses can be submit through the web portal at https://poses.live. After registering on that portal, teams can submit poses either directly through the upload form provided in the web portal, or through an HTTP API at the same domain.

In order to use the HTTP API, teams must first obtain their API token through the web portal. You can find this your team's page. Each request must then include this token in an `Authorization` header:

`Authorization: Bearer $YOUR_API_TOKEN`

The HTTP API supports the following methods:

`GET /api/hello` Says hello to your team. This can be used to verify that your API token works.

`GET /api/problems/$PROBLEM_ID` Retrieves the JSON encoding of the specified problem.

`POST /api/problems/$PROBLEM_ID/solutions` Submit a pose. The request body must contain a JSON encoding of a pose. Returns a pose ID.

`GET /api/problems/$PROBLEM_ID/solutions/$POSE_ID` Retrieves information about a submitted pose. This is a JSON object with the following attributes:

- `state`: Either `PENDING`, `VALID` or `INVALID`.
- `dislikes`: The number of dislikes, when valid.
- `error`: The error message, when invalid.

Regardless of whether you are using the HTTP API or web submission, you cannot submit a pose for a problem if you already submitted a pose for that problem within the last five minutes.

4.3 Scoring

For determining a team's score, only the latest submission for each problem is considered. If that submission is a valid pose, the team's score for that specific problem is given by:

$$\left\lceil 1000 * \log_2\left(\frac{|vertices| * |edges| * |hole|}{6}\right) * \sqrt{\frac{\text{dislikes}_{best} + 1}{\text{dislikes}_{team} + 1}} \right\rceil$$

$|vertices|$ and $|edges|$ are the number of edges and vertices in the figure of the problem, respectively. $|hole|$ is the number of vertices in the hole. dislikes_{team} is the number of dislikes counted by the judges for the team's pose, and dislikes_{best} is the lowest number of dislikes for this problem among all teams.

A team's total score is the sum of their scores for individual problems.

4.4 Deadlines

As traditional, the contest will have a Lightning Division spanning the first 24 hours. To qualify for the Lightning Division prize, submit your poses by July 10, 2021, 12:00pm (noon) UTC.

To qualify for the Full Division prize, submit your poses by July 12, 2021, 12:00pm (noon) UTC.

In order to qualify for any prizes, your source code must be submitted by the end of the contest as well. You can do this through the web portal.

4.5 Determing the Winner

We will use the same procedure to determine the winner in both the lightning and full divisions, ranking the teams by cumulative score, computed as the sum of scores for each task.

4.6 The Judges' Prize

The judges' prize will be picked by the contest organisers. All entries in both the full and lightning divisions are eligible for the judges' prize.

5 Bonuses

Each brain wall problem may have specific locations that are preferred by the judges. Poses that manage to place a vertex at these specific locations are awarded **bonuses**. Each awarded bonus unlocks a certain advantage for a specific puzzle.

Note that even though multiple bonuses can be available to use in a given problem, participants may only use one per pose.

5.1 Submission invalidation

Keep in mind that when using bonuses, submitting a pose that does not unlock certain bonuses may **invalidate other poses, which can in turn invalidate more poses**.

On the other hand, submitting poses that unlock certain bonuses may **validate** other poses transitively as well, if these other poses depended on these bonuses.

Validation based on bonuses always uses the latest submission for each problem. The order in which submissions for different problems are submitted does not matter.

5.2 Wire format

The JSON objects for problems and poses are extended to support awarding and using bonuses.

Problem A problem JSON object may contain a `bonuses` property. This holds an array of JSON objects. Each of the objects in this array contains the following properties:

- `position`: The point on which a vertex must be placed to unlock the bonus.
- `bonus`: A string representing the type of bonus that can be unlocked.
- `problem`: The ID of the problem in which this bonus can be used once it has been unlocked.

Pose A pose JSON object may contain a `bonuses` property. This holds an array of JSON objects. Each of the objects in this array contains the following properties:

- `bonus`: A string representing the type of bonus that is used.
- `problem`: The ID of the problem in which this bonus has been unlocked.

In addition to `bonus` and `problem`, some bonuses may require additional properties indicating how the pose uses the bonus.

6 Available bonuses

6.1 GLOBALIST

Enabling the `GLOBALIST` bonus relaxes constraint (b) on the amount edges can be compressed or stretched. Rather than having an constraint for each edge individually, you can use a global epsilon budget. This global epsilon budget is the number of edges in the original figure multiplied by ε.

$$\sum_{(i,j)\in edges}\left|\frac{d(v_i',v_j')}{d(v_i,v_j)}-1\right|\leq\frac{|edges|\cdot\varepsilon}{1,000,000}$$

6.2 BREAK_A_LEG

Turning on `BREAK_A_LEG` allows you to specify a specific edge (i,j) that is broken in half at its midpoint; resulting in two smaller edges connected to a new vertex. The position of this new vertex must be added after the vertices of the existing positions.

Constraint (b) is updated for these two new edges. If we assume that k is the index of the newly added vertex, then this means we broke edge (i, j) into new edges (i, k) and (j, k). The edge length constraint on $d(v_i, v_j)$ is replaced by the following constraints:

$$\left| \frac{4d(v_i', v_k')}{d(v_i, v_j)} - 1 \right| \leq \frac{\varepsilon}{1,000,000}$$

$$\left| \frac{4d(v_j', v_k')}{d(v_i, v_j)} - 1 \right| \leq \frac{\varepsilon}{1,000,000}$$

When a BREAK_A_LEG bonus is used, objects in the array in the bonuses property of the JSON format for a pose must specify an additional edge property. edge must be an array in the shape of [i, j] where i and j are the indices of the vertices between which you want to break the edge.

Good luck and have fun!!!!!